

Simplifying Problems with Canonical Transformations - the HO again:

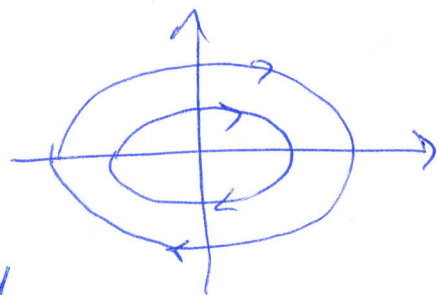
$$H = \frac{p^2}{2m} + \frac{1}{2} m \omega^2 q^2$$

$$\Rightarrow \dot{p} = -m\omega^2 q, \quad \dot{q} = p/m$$

$$\Rightarrow q(t) = A \cos(\omega(t - t_0)), \quad p = -m\omega A \sin(\omega(t - t_0)),$$

with A, t_0 integration constants.

Flows in phase space are ellipses:



Make a canonical transformation & mix up q 's and p 's:

$$(q, p) \rightarrow (\theta, I)$$

new "position" new "momentum"

$$q = \sqrt{\frac{2I}{m\omega}} \sin \theta, \quad p = \sqrt{2Im\omega} \cos \theta$$

(looks a bit odd, but will be useful)

i) Check poisson brackets: It's correct to check

→ discuss complex version in ~~lecture~~ problem to highlight parallels to treatment in QM)

$$\begin{aligned} \{q, p\}_{(\theta, I)} &= \left\{ \frac{\partial q}{\partial \theta} \frac{\partial p}{\partial I} - \frac{\partial p}{\partial \theta} \frac{\partial q}{\partial I} \right\} \\ &= \underbrace{\sqrt{\frac{2}{m\omega}} \cdot \sqrt{2m\omega}}_{=2} \left\{ \sqrt{I} \sin \theta, \sqrt{I} \cos \theta \right\} \\ &= 2 \left(\left(\sqrt{I} \cos \theta \right) \left(\frac{1}{2\sqrt{I}} \cos \theta \right) - \left(-\sqrt{I} \sin \theta \right) \left(\frac{1}{2\sqrt{I}} \sin \theta \right) \right) \\ &= \cos^2 \theta + \sin^2 \theta = 1 \quad \checkmark \end{aligned}$$

(Check that $M J M^T = J$ as an exercise, where

$$M = \begin{pmatrix} \partial \theta / \partial q & \partial \theta / \partial p \\ \partial I / \partial q & \partial I / \partial p \end{pmatrix} = \begin{pmatrix} m\omega/p \cos^2 \theta & -m\omega q/p^2 \cos^2 \theta \\ m\omega q & p/m\omega \end{pmatrix}$$

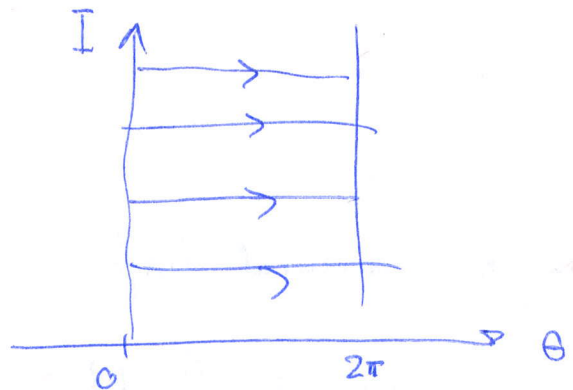
Now look at H in new variables:

$$H = \frac{p^2}{2m} + \frac{1}{2} m \omega^2 q^2 = \frac{1}{2m} (2m\omega I) \sin^2 \theta + \frac{1}{2} m \omega^2 \frac{2I}{m\omega} \cos^2 \theta = \omega I$$

$$\Rightarrow \frac{\partial H}{\partial \theta} = 0, \quad \dot{\theta} = \frac{\partial H}{\partial I} = \omega, \quad \dot{I} = -\frac{\partial H}{\partial \theta} = 0 \Rightarrow I = \text{const.}$$

↑
↑
 "coordinate" "momentum"

How does this look in phase space?



Checking dimension, we see that I has dimensions energy \times time, like the action - thus, (θ, I) are referred to as action-angle variables.

\hookrightarrow This "straightening" of the flow can be done ~~for integrable~~ ^{not} for all systems. If it's possible, we have

$$(q_i, p_i) \rightarrow (\theta_i, I_i)$$

and $H = H(I_i)$, but no θ -dependence. Thus

$$\dot{\theta}_k = \frac{\partial H}{\partial I_k} = \omega_k(I_i) \Rightarrow \theta_k(t) = \omega_k t + \text{const.}$$

If such a transformation is possible, the system is integrable.

For bounded motion, the θ_i are scaled to $0 \leq \theta_i \leq 2\pi$,

and (θ_i, I_i) are called action-angle variables!